

Run old games on old hardware and learn new things!

Yocto Project Workshop at Embedded Recipes 2025

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Root Commit

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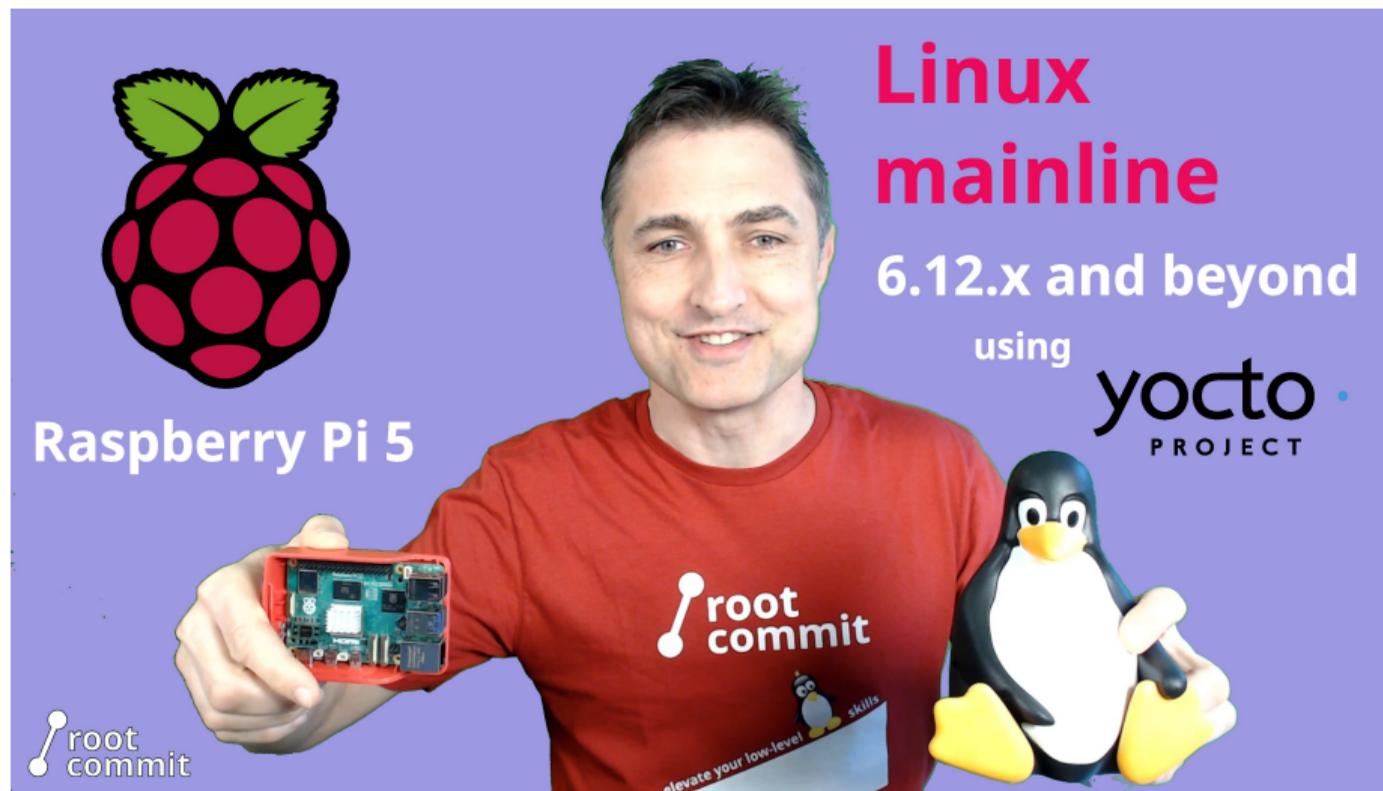
Embedded Linux consultant and trainer

- <https://rootcommit.com/about/michael-opdenacker/>
- Former founder of Bootlin
- New founder of Root Commit
- Offering embedded Linux training courses with a focus on practical activities, interactivity and learning techniques.
<https://rootcommit.com/training/>
- Sharing training materials under CC-BY-SA license
- Free Software enthusiast and advocate 
- Real dream job: become a famous video maker, but not quite there yet 😊



For the OE workshop 2025 in Brussels,
I wanted to test the latest mainline kernel on these boards:

- genericarm64 machine
- BeagleBone Black
- BeaglePlay
- Raspberry Pi 5



<https://www.youtube.com/watch?v=AbNctm6CF4E>

- Recording: OBS — Open Broadcaster Software
<https://obsproject.com/>
- Editing: Kdenlive
<https://kdenlive.org/>
- Even using an Elgato Stream Deck for switching scenes:
Very well supported on GNU/Linux with
<https://github.com/StreamController/StreamController>



https://www.youtube.com/watch?v=kIJ0j_6JImk

Run Mainline Linux
Kernel on your PC

AlpOSS
Alpes open source software



<https://www.youtube.com/watch?v=zeDCODvmo14>

- Technical part: turned out to be easy
Once I got my hand on the necessary cables
- Video marketing part: much more complicated
Good to have a captive audience here 😊
- <https://www.youtube.com/shorts/w-N3yh5U8rw>



- Very simple, just based on `kernel.bbclass`
- Supports one configuration per board:

```
/tmp/linux-mainline tree linux-mainline-6.14+git
linux-mainline-6.14+git
├── beagleboard
│   └── defconfig
├── raspberrypi0-2w-mainline
│   └── defconfig -> ../raspberrypi5-mainline/defconfig
├── raspberrypi2b-mainline
│   └── defconfig
├── raspberrypi3b-mainline
│   └── defconfig -> ../raspberrypi5-mainline/defconfig
├── raspberrypi3b-plus-mainline
│   └── defconfig -> ../raspberrypi5-mainline/defconfig
└── raspberrypi5-mainline
    └── defconfig
```

7 directories, 6 files

```
/tmp/linux-mainline
```

- Alternative: meta-linux-mainline layer by Paul Barker
<https://github.com/betafive/meta-linux-mainline>

```
linux-mainline_6.14.bb
```

```
KVER := "${PV}"
require linux-mainline.inc
SRC_URI:append:raspberrypi5-mainline = " file://defconfig"
SRC_URI:append:raspberrypi0-2w-mainline = " file://defconfig"
SRC_URI:append:raspberrypi3b-plus-mainline = " file://defconfig"
SRC_URI:append:raspberrypi3b-mainline = " file://defconfig"
SRC_URI:append:raspberrypi2b-mainline = " file://defconfig"
SRC_URI:append:beagleboard = " file://defconfig"
```

```
linux-mainline.inc
```

```
linux-mainline.inc
DESCRIPTION = "Mainline Linux kernel"
LICENSE = "GPL-2.0-only"
LIC_FILES_CHKSUM = "file://COPYING;md5=6bc538ed5bd9a7fc9398086ae
dcd7e46"
inherit kernel

S = "${WORKDIR}/git"
SRC_URI = "git://git.kernel.org/pub/scm/linux/kernel/git/stable/
linux.git;branch=linux-${KVER}.y;protocol=https"
SRCREV = "${AUTOREV}"
PV = "${KVER}+git"
PROVIDES = "virtual/kernel"
```

- Quite simple too
- But no class for U-Boot, had to include files from the standard U-Boot recipe

```
u-boot-mainline_2024.07.bb
```

```
require recipes-bsp/u-boot/u-boot-common.inc
require recipes-bsp/u-boot/u-boot.inc
PROVIDES = "virtual/bootloader"
RPROVIDES:${PN} = "u-boot"

# U-Boot 2024.07
SRCREV = "3f772959501c99fbe5aa0b22a36efe3478d1ae1c"
UBOOT_MACHINE:beagleboard = "omap3_beagle_defconfig"

DEPENDS += "bc-native dtc-native gnutls-native
python3-pyelftools-native"
```

```
beagleboard.conf
```

```
PREFERRED_PROVIDER_virtual/xserver ?= "xserver-xorg"
MACHINE_EXTRA_RRECOMMENDS = "kernel-modules"
EXTRA_IMAGEDEPENDS += "virtual/bootloader"
DEFAULTTUNE ?= "cortexa8hf-neon"
include conf/machine/include/arm/armv7a/tune-cortexa8.inc

IMAGE_FSTYPES += "tar.bz2 wic wic.bmap"
WKS_FILE ?= "beagleboard.wks"
MACHINE_ESSENTIAL_EXTRA_RDEPENDS += "kernel-image kernel-devicetree"
do_image_wic[depends] += "mtools-native:do_populate_sysroot dosfstools-native:do_populate_sysroot virtual/bootloader:do_deploy"

SERIAL_CONSOLES ?= "115200;ttyS2"

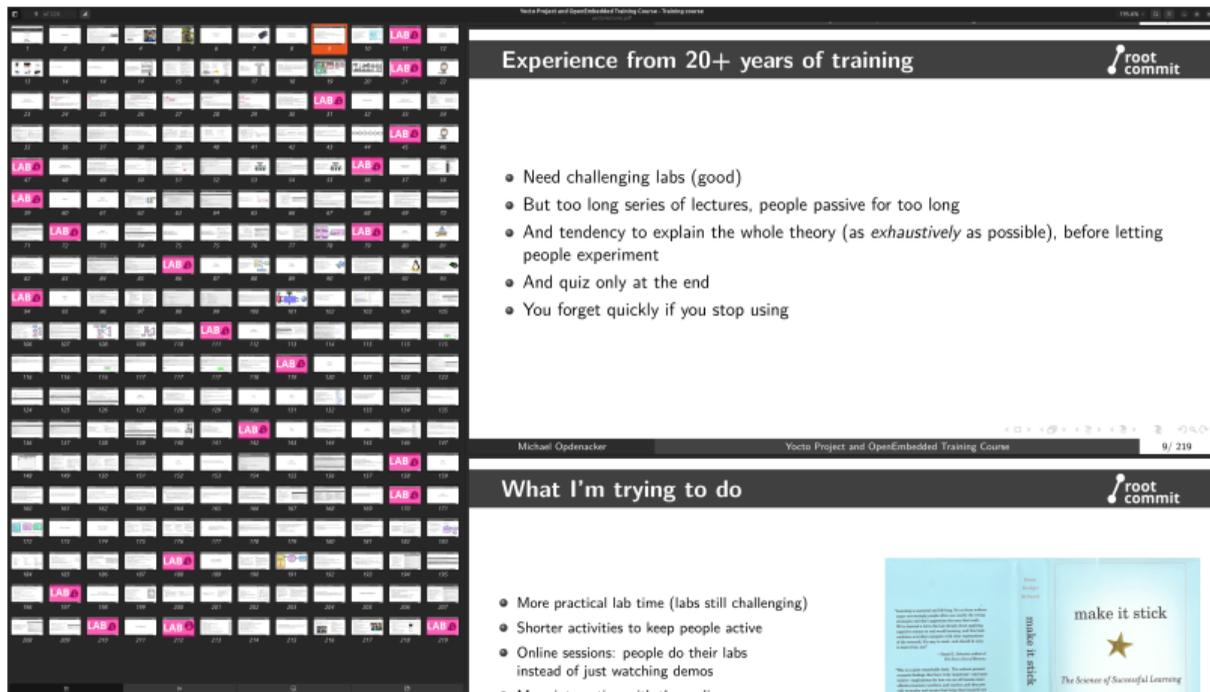
PREFERRED_PROVIDER_virtual/kernel ?= "linux-mainline"
PREFERRED_VERSION_linux-mainline ?= "6.14%"
KERNEL_IMAGETYPE = "zImage"
KERNEL_DEVICETREE = "ti/omap/omap3-beagle.dtb"

PREFERRED_PROVIDER_virtual/bootloader = "u-boot-mainline"
PREFERRED_VERSION_u-boot-mainline = "2024.07"
SPL_BINARY = "MLO"
UBOOT_SUFFIX = "img"

MACHINE_FEATURES = "usb gadget usbhost vfat alsa"

DTB_FILES = "omap3-beagle.dtb"
IMAGE_BOOT_FILES ?= "u-boot.${UBOOT_SUFFIX} ${SPL_BINARY} ${KERNEL_IMAGETYPE} ${DTB_FILES}"
```

- Reused from an old, no longer supported layer
- More complicated, but can include all settings put otherwise in `conf/local.conf`



Experience from 20+ years of training

- Need challenging labs (good)
- But too long series of lectures, people passive for too long
- And tendency to explain the whole theory (as *exhaustively* as possible), before letting people experiment
- And quiz only at the end
- You forget quickly if you stop using

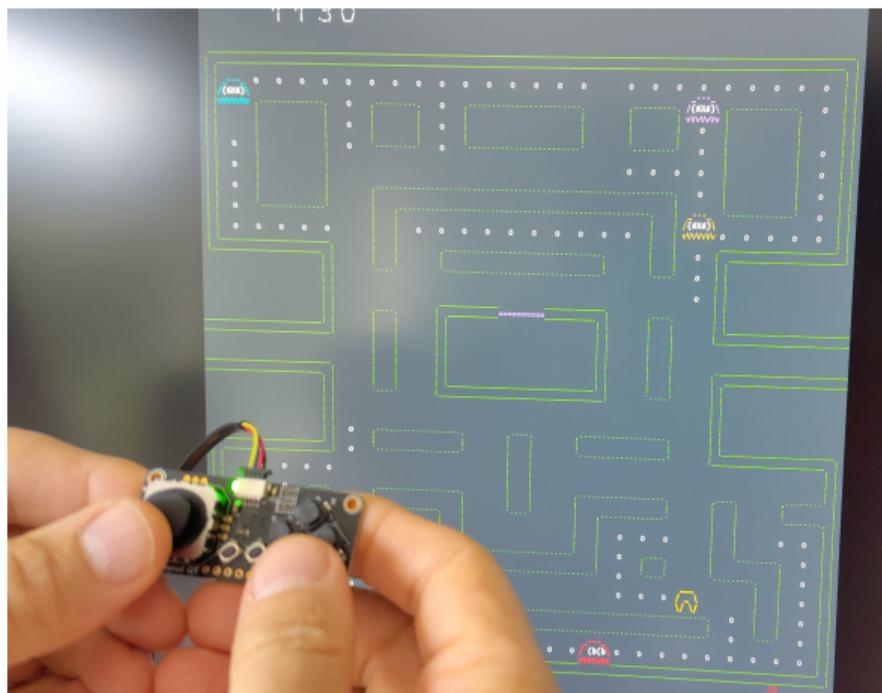
What I'm trying to do

- More practical lab time (labs still challenging)
- Shorter activities to keep people active
- Online sessions: people do their labs instead of just watching demos
- More interactive with the audience

make it stick
The Science of Successful Learning

Creative-Commons BY-SA-4.0 materials: <https://rootcommit.com/training/yocto>
220 pages of lectures, 18 practical labs, on TI BeaglePlay and QEMU

Playing Old ASCII Games With an I2C Joystick





*Talk proposals with ASCII
games are guaranteed to be
accepted*

SP-STUDIO.DE

- `devtool` really made it easy to create recipes for old ascii games
- MyMan: <https://github.com/kragen/myman/>
Last modified 16 years ago (qualified!)
 - Managed to compile it by adding Autotools to the sources: <https://github.com/michaelopdenacker/myman>
 - Then developed a patch to drive the game from a joystick
- vitetris: <http://victornils.net/tetris/>
 - Typically 6 years old, but still maintained 😞
 - Hand made Makefile, not targeting cross-compilation
 - Had to define custom tasks

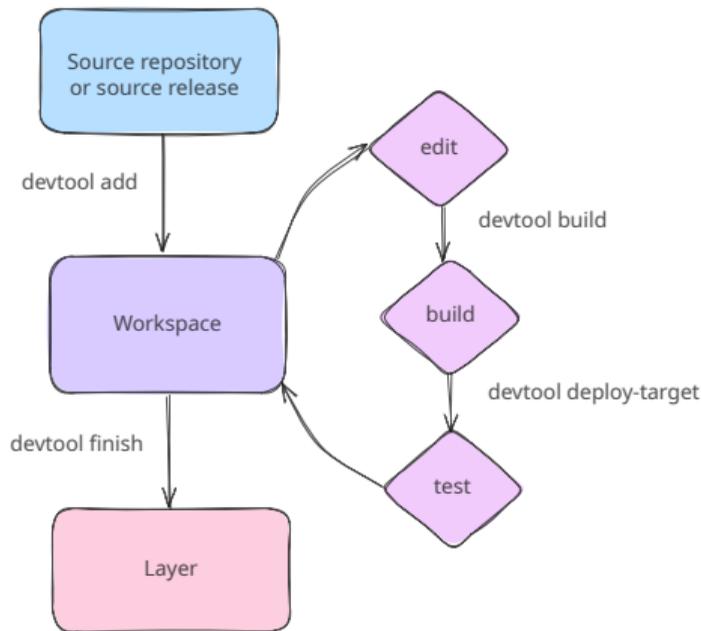
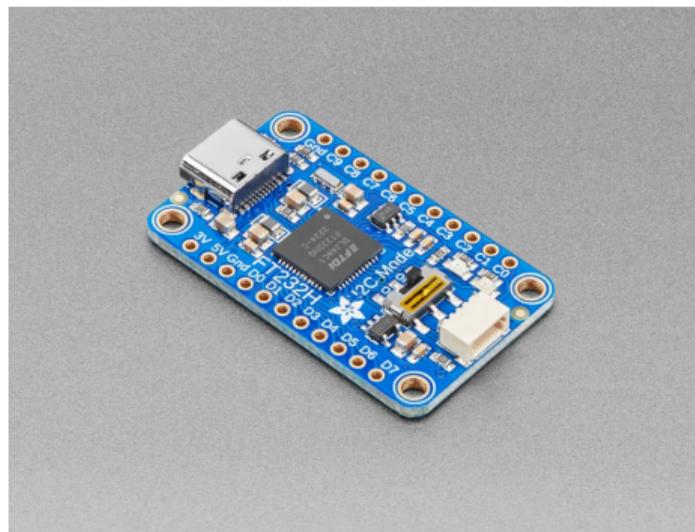


Diagram created with <https://excalidraw.com/> — Open Source of course!

- Was looking great — about to solder expansion headers
- But I2C pins are 1.8V 😬
Same issue on my Panda Board.
- Didn't have time to find level shifters
- Also had an Adafruit USB-I2C device
But only supported in userspace 😱
Found an experimental kernel driver. Haven't managed to fully fix it yet (devices detected though).



Adafruit FT232H breakout:
<https://www.adafruit.com/product/2264>

- Looking good — 3.3V I2C
 - But serial port only through USB (onboard FTDI chip)
 - Good idea at the time, but with a USB mini-AB connector 🤪
 - No time to make the other serial ports work
- Will run the demo on BeaglePlay instead



```
u-boot-ti-staging_2025.01%.bbappend
```

```
FILESEXTRAPATHS:prepend := "${THISDIR}/files:"
```

```
SRC_URI += "file://0001-k3-am625-beagleplay.dts-connect-Adafruit-mini-I2C-ga.patch"
```

```
files/0001-k3-am625-beagleplay.dts-connect-Adafruit-mini-I2C-ga.patch
```

```
From b72870f4b87e2f103ab8a7ef451e85ad5526f182 Mon Sep 17 00:00:00 2001
```

```
From: Michael Opdenacker <michael.opdenacker@rootcommit.com>
```

```
Date: Tue, 15 Apr 2025 05:16:21 +0200
```

```
Subject: [PATCH] k3-am625-beagleplay.dts: connect Adafruit mini I2C gamepad
```

```
Signed-off-by: Michael Opdenacker <michael.opdenacker@rootcommit.com>
```

```
---
```

```
 dts/upstream/src/arm64/ti/k3-am625-beagleplay.dts | 7 +++++-
```

```
 1 file changed, 6 insertions(+), 1 deletion(-)
```

```
diff --git a/dts/upstream/src/arm64/ti/k3-am625-beagleplay.dts b/dts/upstream/src/arm64/ti/k3-am625-beagleplay.dts
```

```
index 9d8f7be53d0..2642b02046d 100644
```

```
--- a/dts/upstream/src/arm64/ti/k3-am625-beagleplay.dts
```

```
+++ b/dts/upstream/src/arm64/ti/k3-am625-beagleplay.dts
```

```
@@ -564,8 +564,13 @@
```

```
 &mcu_i2c0 {
```

```
     pinctrl-names = "default";
```

```
     pinctrl-0 = <&i2c_qwiic_pins_default>;
```

```
-     clock-frequency = <100000>;
```

```
+     clock-frequency = <400000>;
```

```
     status = "okay";
```

```
+
```

beagleplay-gaming.yml

```
header:
  version: 14

machine: beagleplay-gaming
distro: asciigaming
target: core-image-gaming

repos:
  poky:
    url: git://git.yoctoproject.org/poky.git
    commit: dcb242eb1926f393fb08738875232824e69e11e4
    layers:
      meta:
  meta-arm:
    url: https://git.yoctoproject.org/git/meta-arm
    commit: 3cadb81ffaa9f03b92e302843cb22a9cd41df34b
    layers:
      meta-arm:
      meta-arm-toolchain:
  meta-ti:
    url: https://git.yoctoproject.org/git/meta-ti
    commit: 05609ed6e6441c5549496e31b6a28da3a105a7bf
    layers:
      meta-ti-bsp:
  meta-openembedded:
    url: https://git.openembedded.org/meta-openembedded
    commit: edd1a1e284fdbc80cd48d411f235d47f23bc27ae
    layers:
      meta-oe:
  meta-homebrew:
    url: file:///home/mike/yocto-labs/meta-homebrew
    commit: c3ad510802246f1e0d4630186f28b714262d5ebb
  meta-mainline:
    url: file:///home/mike/yocto-labs/meta-mainline
    commit: 7668accbbb44815e985c3e94ac66e943781b5402
```

- Super easy when mainline supports a board
Also true with recent boards with early Linux support
- Only one (Kas) file to share to let others build an image too
- U-Boot is a little less easy, as you have to use U-Boot recipe includes
- devtool is great to create recipes and applications at the same time
- Can be worth it to add Autotools to old recipes
- Old hardware has old connectors, didn't realize
- And sometimes obsolete operating conditions (like 1.8V), making it hard to use recent accessories.

→Yocto is great to keep old hardware busy... and people too!

Questions? Comments?

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- Signal: rootcommit.01

- Slides available under the CC-By-SA 4.0 license
<https://rootcommit.com/pub/conferences/2025/yocto-workshop-nice/yocto-old-hardware/>
- Sources (\LaTeX):
<https://gitlab.com/rootcommit/yocto-old-hardware/>